

ELECTRIC PUSHER - PULLERS

Our mod. TR 2 RC and TR 4 RC pusher-pullers can be controlled directly by the operator or via remote control.

When used for towing, the operator uses the tiller and accelerator and controls the speed of the machine, which tows groups of caddies connected in some way to each other; when used for pushing, the steering wheel is idle. The driver operates the driving system via remote control, which requires direction and speed settings. The machines have a special structure that houses the fixed wheels of the caddie connected to the row of caddies, each of which fits into the other. The direction of advancement is enabled by the operator, who steers the first in the row.

The machines operate in a similar way but differ in their dimensions, pulling/pushing capacity, operating autonomy, wheel dimensions.





CHASSIS: In electric arc welded steel sheet forming a rigid bearing structure.

DRIVE UNIT: Axle with differential driven by a powerful A.C. motor.

STEERING SYSTEM: By tiller and control box containing butterfly switches for selecting gears and speeds, ignition key, battery charge indicator.

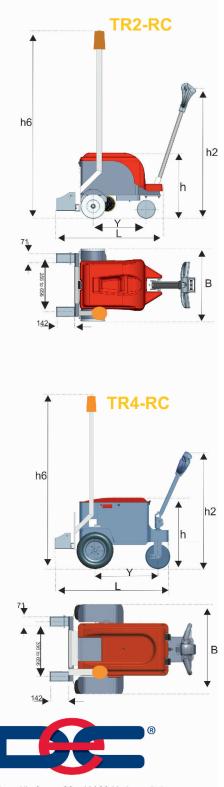
ELECTRIC SYSTEM: With A. C. electronic control unit for maximum control over movements and electronic braking system. Automatic electric parking brake.

WHEELS: No-marking superelastic (TR 2), tyred wheels (TR 4).

OPERATING TIME: Four hours (TR 2), six hours (TR 4) with average work load. A high-frequency battery charger can be installed on board on request.

SAFETY DEVICES: The machine conforms to the regulations in force as to components, performance and stability.

CHARACTERISTICS Manifacturer		dim.un.		
Model			TR2	TR4
Platform loading capacity	Naminal capacity	Va		1174
	Nominal capacity	Kg.	1500	3000
Pull capacity	Load nominal capacity Electric/Endothermic	Kg.	Elettr.	Elettr.
Power type	Pedestrian/stand-on/Seated		Pedestrian	Pedestrian
Control type Tyres	Pn - pneum. / se - superel.		1Se-2Se	1Se-2Pn
Wheels	Number front/rear X=drive	Nr.	3 - 1/2x	3 - 1X/2x
Platform dimensions	L x B (lenght x width)	mm.	3 - 1/2	3-1//2/
DIMENSIONS	L X B (length X width)	111111.		
DIMENSIONS	h= machine hody hight	mm.	550	720
	h= machine body hight L= lenght	mm.	750	1000
	B=width	mm.	550	710
	h 3 = feet panel hight	mm.		710
	h 4 = steering/handle hight	mm.		
	h 2 = thiller hight	111111.	1375	1375
	· ·	mm	13/3	13/3
	h 5 = seat hight	mm.		
	h 6 = turning light hight	mm.		
	h 7 = cabin turning light hight	mm.		
	h 1 = cabin hight h 9 = cabin width	mm.		
Turning radius	R1= front min. external	mm.		920
Turning radius	R2=rear min. external	mm.	720	920
	R3=rear min.internal	mm. mm.		
A iala width	U-turn			
Aisle width Hook hight		mm.	220	250-400
0	s = hook center to ground	mm.	220	250-400
PERFORMANCE	Without / with load	Km./h	6-4	6-4
Speed Tractive effort	Continuative work 60'	N.	600	1000
Tractive ellort		N.	900	2000
Cradophility	Max in plane x 5" Without/width	%	10-2	10-2
Gradeability Weight		Kg.	160	350
Axles load	With battery		40-90	150-200
TRACTION	Front/rear with battery	Kg.	40-90	150-200
Wheels	Front diam./ width	mm.	160x50	280x80
vviieeis	Rear diam./ width	mm.	200x80	380x100
Wheelbase			504	705
Trach	y = pitch C posterior wheels center	mm. mm.	470	640
Graund clearence	clearence at half chassis	mm.	65	100
Working brake	Mecc./hydraul./elettr.	111111.	Elettr.	Elettr.
Working brake	Brake axles number	N.	1	1
Darking broke		IN.	Elettr.	Elettr.
Parking brake	Mecc./hydraul./elettr.		1	1
Suspensions POWER SUPPLY	Spring/laf spring/schock absorber		Į.	I
	Tora		Danfanad	Renforced
Battery	Type	\/ /Ab	Renforced	
	Capacity	V./Ah.	2x12/130 (C5)	
Flattala acata a	Weight	Kg.	70	140
Elettric motor	Translation,power S2=60°	Kw.	0,6 AC	0,8 AC
Electric system	electronic control		Inverter AC	Inverter AC
Steering	Mecc./hydraul./elettr.		Manual	Manual
Transmission	Mecc.		Mechanics	Mechanics
Towing hook	manual - automatic	h	Manual	Manual
Autonomy	working hours witm medium work	h.	5/6	7/8



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